

# EPSON RC+ 7.0.1 SP1 Release Notes

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Thank you for using EPSON RC+ 7.0.1. This document contains the latest information for this release. Please read before using this software.

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## Documentation

All RC+ manuals are in PDF format and are installed on the PC hard disk. These manuals are accessible from the EPSON RC+ 7.0 environment Help menu.

## Getting Started

Read the Getting Started chapter in the EPSON RC+ 7.0 User's Guide. This chapter will refer you to the RC700 Controller manual Installation chapter. This contains information for initial connections and start up.

## What's Fixed in version 7.0.1

### General

1. Fixed exception that occurs when you try to use File | Print.
2. Fixed New Folder button for Project | Export.
3. Fixed several captions for German, French, and Chinese languages.
4. Updated the manuals for RC700, Fieldbus, Remote Control, and Vision Guide Hardware.

### Vision Guide

5. Now multiple virtual GigE cameras can be added.
6. Fixed problems for StartPoint and EndPoint when using perpendicular StartPointType or EndPointType.
7. Fixed exception that can sometimes occur when a result for an attached object (CenterPointObject or Frame) is not found.
8. Fixed problem for color camera White Balance wizard. If the previous displayed sequence was using an image file, then there was no live video for white balance.
9. Fixed a problem for Code Reader. Sometimes error -1009 was displayed when you run the object.
10. Fixed SaveImage for monochrome cameras – the image was being saved in 24 bit color format.
11. Fixed several problems for the CV1 Compact Vision System. Firmware 2.1.0.5 is included with the installation. You can upgrade the firmware from Setup | System Configuration | Vision | Camera.

## What's New in version 7.0.0

### General

1. Supports the EPSON RC700 controller.
2. Supports Remote Control Extended I/O, which can be used for PLC control.
3. PG Status view in I/O Monitor.

### Vision Guide

4. New multi-search feature. Several tools can automatically search using all results of an attached object.

5. Added new tools: Line Finder, Arc Finder, Defect Finder.
6. Supports rotated and circular search areas for Blob, Correlation, Geometric.
7. Supports GigE vision cameras and Compact Vision cameras.
8. Supports higher resolution cameras (3M and 5M).
9. Sequence and calibrations can now be imported from other projects.
10. Supports offline vision. All vision functions can be used offline (without a controller). Vision commands can be executed in virtual controllers.
11. Added pass type and Passed result.
12. Now any color can be used for pass, fail, or label background.

### GUI Builder

13. Forms can now be imported from other projects.

## RC+ API 7.0

### General

RC+ API 7.0 was named VB Guide in previous EPSON RC+ products.

### ***Using with Visual Studio 2010 and .NET Framework 4.0***

If you create an application using Visual Studio 2010 and the target framework version is 4.0, then you need modify the project to allow SpelNetLib70.dll to be used. SpelNetLib70.dll was created with .NET Framework 3.5. By default, applications that target .NET Framework 4.0 cannot load assemblies from previous .NET Framework versions. You must add and modify the app.config file for the solution and set the useLegacyV2RuntimeActivationPolicy property.

For VB and C#:

1. In Solution Explorer, check if app.config exists. If it does, go to step 4.
2. From the Project menu, select Add New Item.
3. Select Application Configuration File and click Add. The app.config XML file will appear.
4. In the app.config file, add the following XML code inside the configuration property.

```
<configuration>
  <startup useLegacyV2RuntimeActivationPolicy="true">
    <supportedRuntime version="v4.0"/>
  </startup>
</configuration>
```

For VC++:

1. Create a config file for the application that uses the same name as the exe file with ".config" appended. For example, if you exe file name is myapp.exe, then the config file would be named myapp.exe.config.

2. In the config file, add the configuration code:

```
<configuration>
  <startup useLegacyV2RuntimeActivationPolicy="true">
    <supportedRuntime version="v4.0"/>
  </startup>
</configuration>
```

3. Copy the config file to both the debug and release folders. You can use a post build event that performs this automatically. For an example, see the Connectivity 7.0 VC++ demo project.

### ***Creating 32 bit application on 64 bit Windows***

To successfully create a Connectivity 7.0 32 bit application on 64 bit Windows, you must set the Visual Studio build target to x86 (32 bit). When using Visual Studio Express versions, you will need to first create the x86 target after enabling Expert Mode.

### ***Executing Spel commands within a button click event***

In .NET, if you execute a method in a button click event, you cannot click another button to execute another method on the first click. For example, if you execute the Go method in a button click event, and attempt to click another button to execute the Abort method, the second button will not respond the first time. This is true even if Connectivity 7.0 is not used. Instead, use the button MouseDown event to execute the Go method, or execute Spel commands in a separate thread as described in the following topic.

### ***Executing Spel motion commands in a separate thread***

If you will be executing Spel motion commands from your .NET application, it is recommended that you execute them in a separate thread. This will allow other methods such as Abort to be executed from other buttons. The example below shows a separate thread for Spel motion commands.

```
private void btnStartCycle_Click(object sender, EventArgs e)
{
    btnStartCycle.Enabled = false;
    btnStopCycle.Enabled = true;
    m_stop = false;
    m_spel.ResetAbort();

    // Start the robot cycle
    System.Threading.Thread t = new System.Threading.Thread(RobotCycle);
    t.Start();
}

private void btnStopCycle_Click(object sender, EventArgs e)
{
    m_stop = true;
    m_spel.Abort(); // Optional. This will immediately stop the cycle
    btnStopCycle.Enabled = false;
    btnStartCycle.Enabled = true;
}
```

```
}  
  
private void RobotCycle()  
{  
    try  
    {  
        do  
        {  
            m_spel.Jump("pick");  
            m_spel.On("GripOn");  
            m_spel.Delay(100);  
            m_spel.Jump("place");  
            m_spel.Off("GripOn");  
            m_spel.Delay(100);  
        } while (!m_stop);  
    }  
    catch (SpelException e)  
    {  
        // If the error is not "Command aborted by user",  
        // then show the error message  
        if (e.ErrorNumber != 10101)  
            MessageBox.Show("Spel error occurred¥n¥n" + e.Message);  
    }  
}
```

## Vision Guide 7.0

### ***ImageFile Property***

The EPSON Smart Camera supports one image file stored in each camera project. When an ImageFile is specified for a sequence, it is copied to the camera when the sequence is selected from the Vision Guide GUI.

You can use the SaveImage property to save an unlimited number of images on the PC.

### ***Using one camera from two controllers***

The EPSON Smart Camera supports two vision projects. Each vision project can be used by one controller, so two controllers can use the same camera. Project 1 is used by default. To use project 2, change the camera project number from RC+ Project | Properties | Vision.

### ***Offline Mode***

When you open the Vision Guide window, RC+ attempts to communicate with the Smart Cameras configured in Setup | Vision. If communication cannot be initiated, a message box is displayed stating that one or more Smart Cameras cannot be connected and asking if you would like to open Vision Guide in offline mode. Answer Yes to enter Offline Mode. In Offline Mode, you can edit Sequences, Objects, and Calibrations. To enter Online Mode, close the Vision Guide window, then open it again.

### ***Importing from EPSON RC+ 3.x and 4.x with Vision Guide***

You can import projects that were created in EPSON RC+ 3.x and 4.x that used the Vision Guide option.

To import a project:

1. In EPSON RC+ 7.0, select Project | Import.
2. Select PC and click Next.
3. Select EPSON RC+ 3.x / 4.x for the Project Type.
4. Select the drive and project to import and continue with the wizard.

Please review the following information regarding imported EPSON RC+ 4.x projects:

- Vision calibrations are imported, but the associated calibration data is not imported. You will need to run your calibrations after import.
- the RobotU vision result is changed. In EPSON RC+ 4.x, RobotU was reported with 0 degrees aligned with the robot world Y axis. Now RobotU is reported with 0 degrees aligned with the robot world X axis.
- Maximum NumberToFind is changed. In Vision Guide 7.0, the maximum NumberToFind for any multi-result object is 100. During import, NumberToFind is reduced to 100 if necessary.
- Calibration properties cannot be set at runtime.
- VCalPoints and VCal are not supported. Vision calibrations cannot be executed at runtime.
- Vision model properties cannot be set at runtime.
- VTeach is not supported. Vision models cannot be taught at runtime.

### ***Camera connected to another PC warning message***

Normally, if one PC tries to connect to a Smart Camera that is already connected to another PC or controller, you will see a message box stating this.

However, sometimes if the Ethernet cable is disconnected or if the RC+ process is terminated while connected to a Smart Camera, then on the next connection attempt, you may receive the message described above. In this case, reset the camera from Setup | Vision, or power cycle the camera. Then rebuild the current project using Project | Rebuild. Smart Camera firmware v1.0.0.4 reduces the occurrence of this problem.